An Extreme Point Result for Robust Stability of a Diamond of Polynomials

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Abstract—The main result of this note is that a family of polynomials with real coefficients lying in a diamond is Hurwitz if and only if eight distinguished extreme polynomials are Hurwitz. For the case of complex coefficients, it is shown via counterexample that no analogous extreme point result holds.

I. INTRODUCTION

Motivated by Kharitonov’s seminal theorem [1] on robust stability for a box of polynomials, a number of recent papers have concentrated on the so-called dual problem for a diamond of polynomials; see [2]-[5]. This robust stability problem for diamonds is simply stated as follows: Consider an nth-order polynomial

\[ p(s, q) = q_0 + q_1 s + q_2 s^2 + \cdots + q_{n-1} s^{n-1} + q_n s^n \]  

(1)

with real coefficients \( q_i \), known to lie in the \((n+1)\)-dimensional diamond with center \( q^* = (q_0^*, q_1^*, \ldots, q_n^*) \) and radius \( r > 0 \), i.e., admissible coefficients are described by \( q \in Q \), where \( q = (q_0, q_1, \ldots, q_n) \) and

\[ Q_r = \{ q : |q_0 - q_0^*| + |q_1 - q_1^*| + \cdots + |q_n - q_n^*| \leq r \}. \]  

(2)

In order to guarantee that \( p(s, q) \) has degree \( n \) for all \( q \in Q_r \), it is assumed that

\[ |q_n^*| > r. \]  

(3)

Now, we denote the diamond family by

\[ \mathcal{D} = \{ p(\cdot, q) : q \in Q \} \]

and say that \( \mathcal{D} \) is Hurwitz if \( p(s, q) \) has all its roots in the open left-half plane for all \( q \in Q \). In [2] and [3], it is shown that \( \mathcal{D} \) is Hurwitz if and only if eight distinguished exposed edges of \( \mathcal{D} \) are Hurwitz; note that the number “eight” is independent of the order \( n \). In [4] and [5], the authors consider whether checking a fixed number of edges is also sufficient for the case of complex coefficients and unit circle stability.

The main goal of this note is to prove that there is no need to check the stability of edges—it is necessary and sufficient to check if eight distinguished extreme polynomials are Hurwitz. As discussed in the conclusion of this note, it is also important to note that an analogous extreme point result does not hold for diamonds of complex polynomials. This is demonstrated with an example for which \( \mathcal{D} \) is not Hurwitz but all extreme polynomials in \( \mathcal{D} \) are Hurwitz.

II. THE MAIN RESULT

The main result of this note is easy to describe.

Theorem: The diamond family of polynomials \( \mathcal{D} \) is Hurwitz if and only if the eight extreme polynomials

\[ p_1(s) = p(s, q_1^*) + r; \]
\[ p_2(s) = p(s, q_2^*) - r; \]
\[ p_3(s) = p(s, q_3^*) + r s; \]
\[ p_4(s) = p(s, q_4^*) - r s; \]
\[ p_5(s) = p(s, q_5^*) + r s^{n-1}; \]
\[ p_6(s) = p(s, q_6^*) - r s^{n-1}; \]
\[ p_7(s) = p(s, q_7^*) + r s^n; \]
\[ p_8(s) = p(s, q_8^*) - r s^n \]  

(4)

are Hurwitz.

III. PROOF OF THE MAIN RESULT

To prove the main result, three fundamental lemmas will be used. The first lemma is the edge result which was discussed in the Introduction.

Lemma 1 (See [3] for proof): The diamond family of polynomials \( \mathcal{D} \) is Hurwitz if and only if the eight polynomials

\[ e_1(s, \lambda) = p(s, q_1^* - \lambda) - (1 - \lambda) r s; \]
\[ e_2(s, \lambda) = p(s, q_2^* + \lambda) - (1 - \lambda) r s; \]
\[ e_3(s, \lambda) = p(s, q_3^* - \lambda) + (1 - \lambda) r s; \]
\[ e_4(s, \lambda) = p(s, q_4^* + \lambda) + (1 - \lambda) r s; \]
\[ e_5(s, \lambda) = p(s, q_5^* - \lambda) - \lambda r s^{n-1} - (1 - \lambda) r s^n; \]
\[ e_6(s, \lambda) = p(s, q_6^* + \lambda) + \lambda r s^{n-1} - (1 - \lambda) r s^n; \]
\[ e_7(s, \lambda) = p(s, q_7^* - \lambda) + \lambda r s^n - (1 - \lambda) r s^{n-1}; \]
\[ e_8(s, \lambda) = p(s, q_8^* + \lambda) - \lambda r s^n - (1 - \lambda) r s^{n-1} \]  

(5)

are Hurwitz for all \( \lambda \in [0, 1] \).

The next lemma is a known result relating real and complex Hurwitz polynomials.

Lemma 2 (See [6, page 61] for proof): Consider a real coefficient polynomial \( p(s) \) expressed as

\[ p(s) = f(s^2) + s g(s^2) \]

where \( f(\cdot) \) and \( g(\cdot) \) are also polynomials and assume that \( p(s) \) has positive coefficients. Then, with

\[ \tilde{p}_1(s) = f(js) + j g(js) \]

and

\[ \tilde{p}_2(s) = f(-js) + j g(-js) \]  

(7)

the triple of polynomials \((p_1(s), \tilde{p}_1(s), \tilde{p}_2(s))\) are Hurwitz equivalent; i.e., either all of them are Hurwitz or none of them are Hurwitz.

The next lemma is a minor extension of Lemma 2.1 in [7]; see

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also the paper [8] where a different extension is given. It is worth noting that the proof of Lemma 3 below involves a geometric nature, whereas the original proof in [7] is algebraic in essence, that is, in [7] the Lienard-Chipart criterion is used.

Lemma 3: Let \( p_0(s) \) be a fixed polynomial of order \( n \) with real coefficients. In addition, take \( r > 0, \alpha \in (-1, 1), \beta \in (-1, 1), \) and integer \( i \in (0, n - 1) \) and assume that the polynomial

\[
p(s, \lambda) = p_0(s) + \lambda s^i(\alpha + \beta s)
\]

has degree \( n \) for all \( \lambda \in [0, 1] \). Then \( p(s, \lambda) \) is Hurwitz for all \( \lambda \in [0, 1] \) if and only if \( p(s, 0) \) and \( p(s, 1) \) are Hurwitz.

Proof: Since necessity is obvious, we proceed to establish sufficiency. We consider the case when \( \alpha = \beta = 1, n \) is odd and \( i = n - 1 \) and simply note that a nearly identical proof applies for the other cases, e.g., when \( i = n - 1 \) and \( n \) is even, then in using Lemma 2 one exploits \( \tilde{p}_2(s) \) rather than \( \tilde{p}_2(s) \) in the argument below.

Indeed, we assume that \( p(s, 0) \) and \( p(s, 1) \) are Hurwitz. Hence, each of these two polynomials has either all positive coefficients or all negative coefficients. We claim that both polynomials must have coefficients of the same sign. To establish this claim, we proceed by contradiction, i.e., suppose \( p(s, 0) \) and \( p(s, 1) \) have coefficients of opposite sign. Then, letting \( a_n(s) \) denote the coefficient of \( s^n \) in \( p(s, 0) = p_0(s) \), it follows that the coefficient of \( s^n \) in \( p(s, \lambda) \) is

\[
a_n(\lambda) = a_n + \lambda r.
\]

Notice that if \( a_n(0) \) and \( a_n(1) \) have opposite sign, it follows that

\[
a_n(\lambda^*) = 0
\]

for some \( \lambda^* \in (0, 1) \). This contradicts the assumption that \( p(s, \lambda) \) has degree \( n \) for all \( \lambda \in [0, 1] \). Henceforth, without loss of generality, we assume that both \( p(s, 0) \) and \( p(s, 1) \) have positive coefficients. As an immediate consequence, it follows that \( p(s, \lambda) \) has positive coefficients for all \( \lambda \in [0, 1] \).

The next step of the proof is to write

\[
p_0(s) = f_0(s^2) + g_0(s^2)
\]

where \( f_0(s) \) and \( g_0(s) \) are polynomials. This leads to

\[
p(s, \lambda) = f_0(s^2) + \lambda s^i s^{n-1} + g_0(s^2) + \lambda s^i s^{n-1}.
\]

Now, in accordance with Lemma 2, it suffices to show that the complex coefficient polynomial

\[
\tilde{p}(s, \lambda) = \left[ f_0(js) + \lambda s^i (js)^{n-1}/2 \right] + \left[ g_0(js) + \lambda r (js)^{n-1}/2 \right]
\]

\[
= \left[ f_0(js) + \tilde{g}_0(js) \right] + \lambda r (js)^{n-1}/2 (1 + j)
\]

is Hurwitz for all \( \lambda \in [0, 1] \). To this end, we first note that we can apply Lemma 2 to the extremes, i.e., Hurwitzness of \( p(s, 0) \) and \( p(s, 1) \) implies that \( \tilde{p}(s, 0) \) and \( \tilde{p}(s, 1) \) are Hurwitz. Now, to establish that \( \tilde{p}(s, \lambda) \) is Hurwitz for all \( \lambda \in [0, 1] \), we proceed by contradiction: If \( \tilde{p}(s, \lambda) \) is not Hurwitz for some \( \lambda \in (0, 1) \), then continuous root dependence on \( \lambda \) dictates that there exists some \( \omega^* \in R \) and \( \lambda^* \in (0, 1) \) such that

\[
\tilde{p}(s, \omega^*, \lambda^*) = 0.
\]

We first rule out the possibility that \( \tilde{p}(s, \omega^*, 0) = 0 \) or \( \tilde{p}(s, \omega^*, 1) = 0 \) or \( \omega^* = 0 \) because this would contradict Hurwitzness of \( p(s, 0) \) and \( \tilde{p}(s, 1) \). Furthermore, noting that the quantity multiplying \( \lambda \) in (9) is nonzero except at \( \omega = 0 \), it follows that for each \( \omega > 0 \), the value set

\[
\tilde{p}(s, \omega, [0, 1]) = \{ \tilde{p}(s, \omega, \lambda) : \lambda \in [0, 1] \}
\]

is a line segment in the complex plane with endpoints \( \tilde{p}(s, \omega, 0) \) and \( \tilde{p}(s, \omega, 1) \) and constant slope \( \tilde{m}(\omega) = 1 \).

To complete the proof, note that (10) implies that the point \( s = 0 \) lies on the relative interior of the line segment \( \tilde{p}(s, \omega^*, [0, 1]) \). Since the polynomials \( \tilde{p}(s, 0) \) and \( \tilde{p}(s, 1) \) are Hurwitz, their angles \( \angle \tilde{p}(s, 0) \) and \( \angle \tilde{p}(s, 1) \) are strictly increasing functions of \( \omega \). Hence, in conjunction with the fact that \( s = 0 \) lies on \( \tilde{p}(s, \omega^*, [0, 1]) \), it follows that for \( \omega > \omega^* \) sufficiently small, the value set has slope \( \tilde{m}(\omega) > \tilde{m}(\omega^*) = 1 \). This, however, contradicts the constancy of \( \tilde{m}(\omega) \). The proof is now complete.

Remark: Note that the restrictions on \( i, \alpha, \) and \( \beta \) are stronger than necessary in order for the conclusion of Lemma 3 to hold. It is quite easy to verify that a stronger version of the lemma holds under the conditions that \( \alpha \) and \( \beta \) are real and \( i \in \{0, 1, 2, 3, \ldots, n - 2, n - 1 \} \).

Now, we are in a position to prove the main result.

Proof of Theorem: First, note that necessity is trivial since each \( p_k(s) \) is a member of \( \mathcal{P} \). To establish sufficiency, we first invoke Lemma 3, i.e., the diamond family of polynomials \( \mathcal{P} \) is Hurwitz if and only if all the edges given in (5) are Hurwitz. Next, observe that by substitution of \( \lambda = 0 \) and \( \lambda = 1 \) into the edge \( e_k(s, \lambda) \), we obtain precisely the eight polynomials \( p(s), p(s), \ldots, p(s) \) for each \( k \). Hence, the remainder of the proof reduces to showing that for each \( k \in \{1, 2, 3, \ldots, 8\} \), \( e_k(s, 0) \) and \( e_k(s, 1) \) being Hurwitz implies that \( e_k(s, \lambda) \) is Hurwitz for all \( \lambda \in [0, 1] \). This is easily accomplished by verifying that each \( e_k(s, \lambda) \) satisfies the preconditions of Lemma 3. This is, for arbitrary \( k \in \{1, 2, 3, \ldots, 8\} \), \( e_k(s, \lambda) \) can be written in the form (8), \( e_k(s, \lambda) \) has degree \( n \) and \( e_k(s, 0) \) and \( e_k(s, 1) \) are Hurwitz.

IV. EXAMPLE

Consider the diamond family \( \mathcal{P} \) of fourth-order polynomials described by

\[
p(s, q) = q_0 + q_1 s + q_2 s^2 + q_3 s^3 + q_4 s^4
\]

with real coefficients \( q_i \) known to lie in the diamond with center

\[
q^* = (q_0^*, q_1^*, q_2^*, q_3^*, q_4^*) = (3.49, 7.98, 6.49, 3.00, 1.00)
\]

and radius \( r = 0.5 \). Since \( q^*_i > r \), it is immediate that all polynomials in this family are fourth order. Therefore, by the main theorem, Hurwitzness of the eight extreme polynomials

\[
p_0(s) = p(s, q^*) + 0.5; \quad p_2(s) = p(s, q^*) - 0.5; \quad p_1(s) = p(s, q^*) + 0.5s; \quad p_4(s) = p(s, q^*) - 0.5s; \quad p_3(s) = p(s, q^*) + 0.5s^2; \quad p_5(s) = p(s, q^*) - 0.5s^2; \quad p_1(s) = p(s, q^*) + 0.5s^4; \quad p_2(s) = p(s, q^*) - 0.5s^4.
\]

is necessary and sufficient for \( \mathcal{P} \) to be Hurwitz. Now, it is straightforward to verify that this is indeed the case; that is, each \( p_k(s) \) has all its roots in the open left-half plane.

For this same example, we now compute a measure of robustness. That is, we compute the largest value of the radius \( r \) for
which Hurwitzness is preserved. Calling this robustness measure $r_{\text{max}}$ we already know from the analysis above that $r_{\text{max}} > 0.5$.

Now, for each $p_i(s)$, let $r_{\text{max}}$ denote the largest value of $r$ such that $p_i(s)$ is Hurwitz. A straightforward computation leads to

$$
\begin{align*}
    r_{\text{max}}_1 &= 6.6978; \\
    r_{\text{max}}_2 &= 3.4900; \\
    r_{\text{max}}_3 &= 9.7150; \\
    r_{\text{max}}_4 &= 6.2050; \\
    r_{\text{max}}_5 &= 10.4867; \\
    r_{\text{max}}_6 &= 1.6471; \\
    r_{\text{max}}_7 &= 0.9467; \\
    r_{\text{max}}_8 &= 1.0000
\end{align*}
$$

from which it follows that

$$
r_{\text{max}} = \min_k r_{\text{max},k} = 0.9467.
$$

V. CONCLUDING REMARKS

In view of the main result in the note, there is a temptation to conjecture that an analogous extreme point result can be given for complex polynomials, i.e., instead of $p(s, q)$ consider a polynomial of the form

$$
p(s, u, v) = \sum_{i=0}^{n} (u_i + jv_i)s^i
$$

where $u = (u_0, u_1, \ldots, u_n)$ and $v = (v_0, v_1, \ldots, v_n)$ lie in diamonds $U$ and $V$ analogous to (2), respectively. It is surprising to note, however, that such a conjecture is false. To this end, the following counterexample is given. Consider a second-order complex polynomial $p(s, u, v)$ with $u = (u_0, u_1, u_2), v = (v_0, v_1, v_2)$, diamond centers given by $u_0^* = -4.3176, u_1^* = 0.0111, u_2^* = 1.2272, v_0^* = 1.8398, v_1^* = 15.1285, v_2^* = 6.3118$, and both real and imaginary radii $r_u = r_v = 1$. It is then straightforward to verify that all polynomials in the family are second order and moreover, there are at most 36 extreme polynomials of the form

$$
\begin{align*}
    p(s, u^*, v^*) &\pm (1 \pm j) \\
    p(s, u^*, v^*) &\pm (1 \pm js) \\
    p(s, u^*, v^*) &\pm (1 \pm j s^2) \\
    p(s, u^*, v^*) &\pm (s \pm j) \\
    p(s, u^*, v^*) &\pm (s \pm js) \\
    p(s, u^*, v^*) &\pm (s \pm j s^2) \\
    p(s, u^*, v^*) &\pm (s^2 \pm j) \\
    p(s, u^*, v^*) &\pm (s^2 \pm js) \\
    p(s, u^*, v^*) &\pm (s^2 \pm j s^2)
\end{align*}
$$

which are all Hurwitz. However, the polynomial $p(s) = p(s, u^*, v^*) + 0.5s - (0.5 + j)$ is a member of the family and has roots $s_1 = -2.3249 - j0.0440$ and $s_2 = 0.0002 - j0.3271$. Hence, the family is not Hurwitz even though all the extremes are Hurwitz.

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REFERENCES


The Solution of a Partially Observed Stochastic Optimal Control Problem in Terms of Predicted Miss

Kurt Holmes and Raymond Rishel

Abstract—The explicit solution of a partially observed LQ-problem driven by a combination of a Wiener process and an unobserved finite state jump Markov process is given.

I. INTRODUCTION

The problem of adaptive control is to design a control system when there is only inexact knowledge of certain system parameters. If these parameters are modeled as random variables or vary in a stochastic manner, it becomes a partially observed stochastic control problem. In [1], Caines and Chen consider a stochastic adaptive control system whose parameters vary according to a finite state jump Markov process. They recognized, by using the nonlinear filtering equations for the conditional probabilities of the parameter states, that the control problem can be converted into a completely observed control problem. Then, they gave a verification theorem for checking that a control is optimal. However, they did not solve any examples and it appears that there have not been any previously solved examples of this type of “adaptive” control system. The purpose of this note is to provide an explicit solution for an LQ-problem of this type.

Applications of the model include guidance problems where the jump Markov process models evasive maneuvers (acceleration values) of the target, or systems subject to a sequence of failures which can be modeled by a jump Markov process.

II. THE PROBLEM

Let $z(t)$ be a finite state jump Markov process with stationary transition probabilities whose values lie in a set of $k$ different